# Learning Realtime One-Counter Automata TACAS 2022

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- 1. Motivation: model checking
- 2. Learning a DFA
- 3. Realtime one-counter automata
- 4. Learning a realtime one-counter automaton
- 5. Implementation and future work

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 $\hookrightarrow$  The family of deterministic finite automata (DFAs) which can be learned by an active learning algorithm, such as  $L^*$ .<sup>1</sup>



Figure 1: Angluin's framework [Angluin, "Learning Regular Sets from Queries and Counterexamples", 1987].



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Main ideas for L^*:
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 $\hookrightarrow$  We add a natural counter.

A realtime one-counter automaton (ROCA) is a tuple  $\mathcal{A} = (Q, \Sigma, \delta_{=0}, \delta_{>0}, q_0, F)$  with:

- Q is the set of states,
- $\blacktriangleright$   $\Sigma$  is the alphabet,
- δ<sub>=0</sub> and δ<sub>>0</sub> are the transition functions:

$$\begin{split} \delta_{=0} : Q \times \Sigma \to Q \times \{0, +1\} \\ \delta_{>0} : Q \times \Sigma \to Q \times \{-1, 0, +1\} \end{split}$$

*q*<sub>0</sub> is the initial state, and
 *F* ⊆ *Q* is the set of accepting states.



An ROCA defines a configuration graph where states are  $Q \times \mathbb{N}$ .



$$(q_0, 0) \xrightarrow{a}_{\mathcal{A}} (q_0, 1) \xrightarrow{b}_{\mathcal{A}} (q_1, 1) \xrightarrow{a}_{\mathcal{A}} (q_1, 0)$$

$$a, = 0, +1$$
  
 $\rightarrow q_0$   $a, > 0, +1$   
 $b, = 0, 0$   $b, > 0, 0$   
 $q_1$   $a, > 0, -1$   
 $b, > 0, 0$   
 $a, = 0, 0$   
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We can show that the language of  $\mathcal{A}$  is

$$\mathcal{L}(\mathcal{A}) = \{a^n b (b^* a)^n \{a, b\}^* \mid n \in \mathbb{N}\}.$$

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Let L be the language of some ROCA A. It is possible to learn an ROCA accepting L in an exponential time and space complexities in |Q| and  $|\Sigma|$ .

What do we want to learn exactly?

<sup>2</sup>Inspired by Neider and Löding, *Learning visibly one-counter automata in polynomial time*, 2010.

V. Bruyère, G. A. Pérez, G. Staquet Learning an ROCA — Equivalence relation Lear

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For DFAs, we learn an equivalence relation called the Myhill-Nerode congruence, from which we can construct the minimal DFA accepting the target language.

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Let  $\mathcal{A}$  be an ROCA accepting L, and  $u, v \in \Sigma^*$ . We say that  $u \equiv v$  if and only if  $\forall w \in \Sigma^*$ , we have<sup>2</sup>

 $uw \in L \Leftrightarrow vw \in L,$  $uw, vw \in Pref(L) \Rightarrow c_{\mathcal{A}}(uw) = c_{\mathcal{A}}(vw).$ 

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We fix a counter limit  $\ell$  and we learn the minimal DFA that accepts L up to  $\ell,$  denoted by  $L_\ell.^3$ 

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Lemma 3

Let  $\mathcal{A}$  be an ROCA accepting L,  $BG(\mathcal{A})$  be its behavior graph,  $\ell$  be a counter limit, and  $\mathcal{H}$  be the minimal DFA accepting  $L_{\ell}$ . Then, if  $\ell$ is large enough, the initial fragments of  $BG(\mathcal{A})$  and  $\mathcal{H}$  are isomorphic.

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Moreover, if  $\ell$  is large enough, it is possible to construct an ROCA accepting L from  $\mathcal{H}$ .

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Let  $\mathcal{A}$  be an ROCA accepting a language  $L \subseteq \Sigma^*$ . Given a teacher for L, which answers membership, counter value, and (partial) equivalence queries, an ROCA accepting L can be computed in time and space exponential in  $|Q|, |\Sigma|$  and t, where t is the length of the longest counterexample returned by the teacher on (partial) equivalence queries.

Let  $\mathcal{A}$  be an ROCA accepting a language  $L \subseteq \Sigma^*$ . Given a teacher for L, which answers membership, counter value, and (partial) equivalence queries, an ROCA accepting L can be computed in time and space exponential in  $|Q|, |\Sigma|$  and t, where t is the length of the longest counterexample returned by the teacher on (partial) equivalence queries.

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- $\blacktriangleright$   $\mathcal{O}(|Q|t^2)$  equivalence queries, and
- A number of membership (resp. counter value) queries which is exponential in |Q|, |Σ| and t.

 Counter value queries are required, unlike in [Neider and Löding, *Learning visibly one-counter automata in polynomial time*, 2010].

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- Proving that the structure eventually satisfies the constraints we want is a hard task.
  - For instance, the algorithm never stops if we have a single set of separators.

We implemented our algorithm in Java using  $\operatorname{AutomataLiB}$  and  $\operatorname{LearnLiB}.$ 

We evaluated the performance on two types of benchmarks:

- 1. On randomly generated ROCAs.
- 2. On JSON documents.



Figure 5: Experimental results for randomly generated ROCAs.

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For the JSON based benchmarks, the teacher has a JSON schema which details how a document should be structured.

```
ł
1
2
       "type": "object",
       "properties": {
3
            "subList": {
4
5
                 "type": "array",
                 "items": {"$ref": "#"}
6
7
            }
       }
8
9
  }
```

#### Listing 1: A JSON schema.

| Schema | TO<br>(1h) | Time<br>(s) | t     | R      | $ \widehat{S} $ | $ \mathcal{A} $ | $ \Sigma $ |
|--------|------------|-------------|-------|--------|-----------------|-----------------|------------|
| 1      | 0          | 16.39       | 31.00 | 55.55  | 32.00           | 33.00           | 19.00      |
| 2      | 27         | 1045.64     | 12.99 | 57.84  | 33.74           | 44.29           | 14.70      |
| 3      | 19         | 922.19      | 49.49 | 171.94 | 50.49           | 51.16           | 9.00       |

Table 1: Results for JSON documents.

For future work:

- Remove partial equivalence queries by working with more recent learning algorithms, such as TTT by Isberner et al.<sup>4</sup> or L<sup>#</sup> by Vaandrager et al.<sup>5</sup>
- Lowering the complexity.

Currently, we are working on extending the use-case on JSON documents to be usable in practice.

<sup>4</sup>Isberner, Howar, and Steffen, "The TTT Algorithm: A Redundancy-Free Approach to Active Automata Learning", 2014.

<sup>5</sup>Vaandrager et al., "A New Approach for Active Automata Learning Based on Apartness", 2021.

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