### Half-Positional Objectives Recognized by Deterministic Büchi Automata

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#### Zero-sum turn-based games on graphs



Understand the **objectives** for which **simple** strategies suffice to win.

Half-Positional Objectives Recognized by DBA

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# Half-positionality

#### Strategies

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#### Existing results

- Sufficient conditions for half-positionality.<sup>1,2</sup>
- Structural characterization!<sup>3</sup>

<sup>&</sup>lt;sup>1</sup>Kopczyński, "Half-Positional Determinacy of Infinite Games", 2006.

<sup>&</sup>lt;sup>2</sup>Bianco et al., "Exploring the boundary of half-positionality", 2011.

<sup>&</sup>lt;sup>3</sup>Ohlmann, "Characterizing Positionality in Games of Infinite Duration over Infinite Graphs", 2022.

### Objectives

Common class of objectives finitely representable:  $\omega$ -regular objectives.



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#### Here

**Effective characterization** of **half-positional** objectives recognized by **deterministic Büchi automata** (DBA).

DBA recognize a **sub**class of the  $\omega$ -regular objectives.

### Examples

- $C = \{a, b\}.$ 
  - $W = \text{Büchi}(a) = \text{"seeing } a \text{ infinitely often": half-positional.}^4$



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•  $W = \text{Büchi}(a) \cup C^*aaC^{\omega}$ : half-positional.



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#### Main result

**Characterization** of half-positionality of W with a conjunction of **three** conditions.

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- Right: three states, all recognizing different objectives.

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Being "Myhill-Nerode-like" is necessary for half-positionality.

### Conclusion: two corollaries

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Polynomial-time algorithm

**Half-positionality** of W can be **decided** in  $\mathcal{O}(|\mathcal{B}|^4)$  time.

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One-to-two-player, finite-to-infinite lift

If W is half-positional over **finite one-player** graphs, then also in **infinite two-player** games!

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# Thanks!