

**Study Day SRBE-KBVE – 10.06.2022**

**Power Network Digitalization – Impacts on  
Protection, Automation and Control**

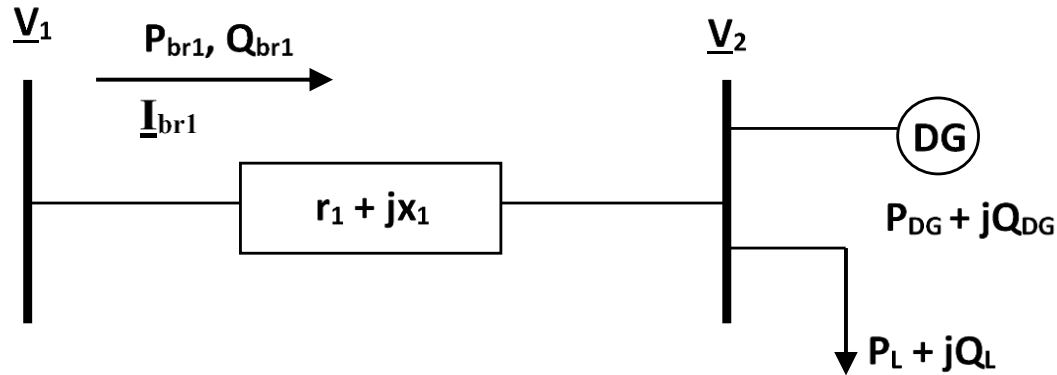
**Voltage control in distribution systems  
using deep reinforcement learning  
in presence of uncertainty**

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## Overview of the presentation

1. Voltage variation problem in distribution systems
2. Uncertainty in distribution system analyses
3. Literature review of voltage control methods
4. Proposed reinforcement learning-based voltage control technique
5. Studied distribution network, test cases and obtained results
6. Conclusion



$$\Delta V_{12} = V_1 - V_2 = r_1 \underbrace{(P_L - P_{DG})}_{P_{br1}} + x_1 \underbrace{(Q_L \pm Q_{DG})}_{Q_{br1}}$$

Due to load demand changes

and DG active power variations,

both voltage rise and drop violations can occur.

## Voltage violations can be managed by:

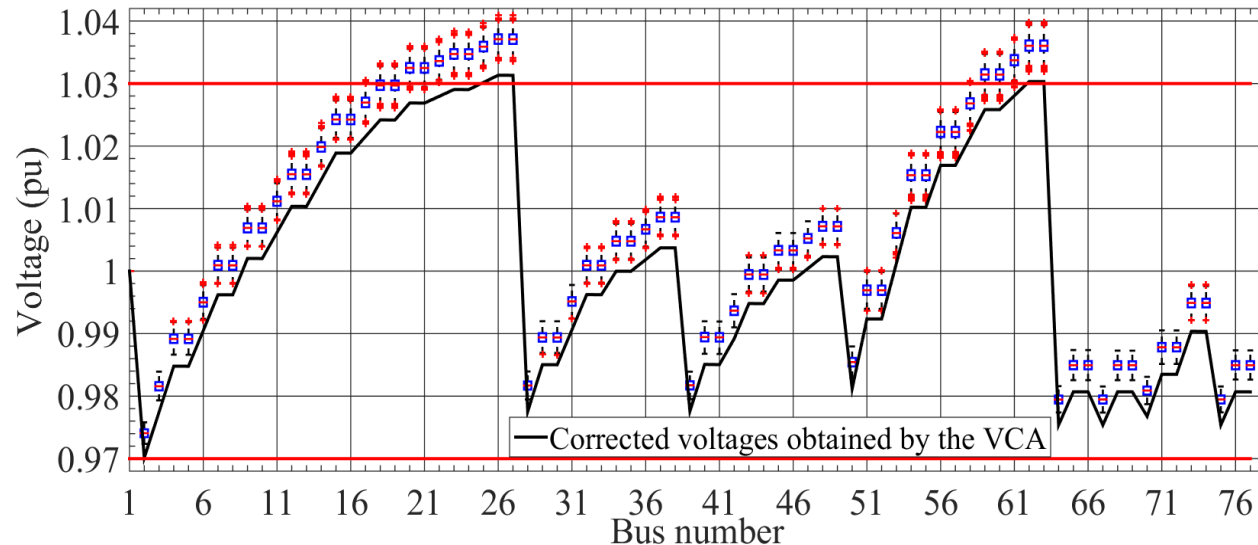
$$\Delta V_{12} = V_1 - V_2 = r_1 (P_L + P_{DG}) + x_1 (Q_L \pm Q_{DG})$$

1. On load tap changer (OLTC)  $\Rightarrow V_1$
2. Reactive power control of DG  $\Rightarrow Q_{DG}$
3. Curtailment of DG active power  $\Rightarrow P_{DG}$
4. Load (demand side) management  $\Rightarrow P_L$
5. Network reconfiguration or reinforcement  $\Rightarrow r_1, x_1$

Due to uncertainty, unobservability and complexity of distribution **networks**, simplified models are **generally** used in the distribution systems:

- 1. Loads are voltage independent**
- 2. Power factors of loads are known**
- 3. Line parameters remain constant**
- 4. Network lines are series impedances**
- 5. Transformers are pure reactances, ...**

The classical simplified network models can mislead analyses and lead to unsafe voltage control decisions [1]



The boxplots show the possible deviations of nodal voltages considering the model uncertainty associated with the loads, lines and transformer

## 1- Based on an Optimal Power Flow (OPF), e.g. [2]

- ❑ OPF can be used as the central decision maker to define the optimal **set-point of control variables** that **minimizes an objective function** while **maintaining operational constraints**.
- ❑ OPF is formulated as a constrained optimization problem:

$$\begin{aligned} \text{Min:} \quad & f(u, x) \\ \text{Subject to:} \quad & g(u, x) = 0 \\ & h(u, x) \leq 0 \end{aligned}$$

- ❑ OPF is a non-linear non-convex problem  $\Rightarrow$  difficult to solve.
- ❑ It **relies on a simplified deterministic** network model.
- ❑  $\Rightarrow$  it **cannot take into account the uncertainty** associated with the network model and its operating point.

## 2- Based on a linearized formulation, e.g. [3-4]

- **Sensitivity analysis** linearizes the relationships between control variables and node voltages (and branch currents).
- Linearized voltage control problem can be formulated as:

$$\text{Min: } \mathbf{C}^T \mathbf{x}$$

$$\mathbf{A} \mathbf{x} \leq \mathbf{b}$$

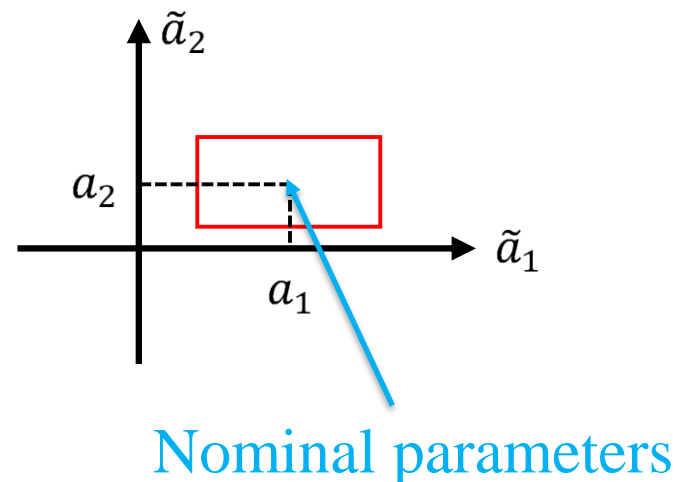
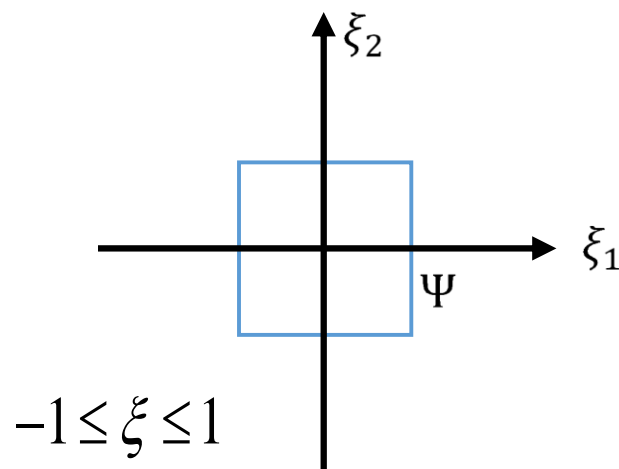
$$\mathbf{l}_b \leq \mathbf{x} \leq \mathbf{u}_b$$

- $\mathbf{C}^T$ : coefficients reflecting costs of control actions,
  - $\mathbf{x}$ : vector of control variables to remove voltage violations,
  - $\mathbf{A}$ : sensitivity matrix,  $\mathbf{b}$ : vector of required voltage changes,
  - $\mathbf{l}_b, \mathbf{u}_b$ : bounds on control variables.
- It relies on linearized equations => **entails simplification errors.**
  - It **cannot handle the uncertainty** impacts.



### 3- Based on Robust Optimization (RO), e.g. [5]

- ❑ The robust optimization can be adopted to deal with the voltage control problem **subject to uncertainty**.
- ❑ RO considers that the entries of matrix  $A$  are subject to uncertainty, defined by  $a_{ij} = a_{ij} + \xi_{ij} a_{ij}$
- ❑ It finds a solution that is robust against the **worst realization** of uncertainty => could be **too conservative and costly**.



#### 4- Based on Chance-Constrained Optimization (CCO), e.g., [6]

- CCO aims to immunize the constraint  $i$  subject to uncertainty **with a confidence level**  $(1 - \epsilon_i)$ :

$$P\left(\sum_{j=1}^n \tilde{a}_{ij}x_j \leq \tilde{b}_i\right) \geq 1 - \epsilon_i$$

- It permits to **adjust the desired level of conservatism** against uncertainty by changing  $\epsilon_i$ .
- The complexity of CCO formulation increases when there are **several coupled constraints subject to uncertainty**.
- **Difficult** to be applied to **large-scale** distribution networks.

- RL principles consist in **an agent interacting with an environment** over a number of discrete time steps until the agent reaches a terminal state.
- At each time step, the **agent observes a state from the state space**, and **selects an action** according to its policy.
- The agent ends up in the next state while **receiving a reward** based on its taken action.
- During the training, **the goal of the agent is to learn the best policy** i.e., to select actions that **maximize the future reward**.
- An agent generally starts from an initial (poor) policy.
- It **progressively learns** through many experiences/interactions with the environment **how to maximize its rewards**.
- The performance of the trained agent is evaluated in the test phase on the **unseen new observations**.

## In the context of voltage control problem:

- **Agent** is the central control algorithm that manages the voltage limits;
- **Environment** is the distribution network (subject to the different sources of uncertainty);
- **Action space** includes the control decisions (DG power set-points & OLTC action) to manage the voltage limits;
- **State space** contains the monitored voltages, DG powers and OLTC set-point;
- **Reward function** consists of the voltage violation **costs** as well as the **control decision costs**:

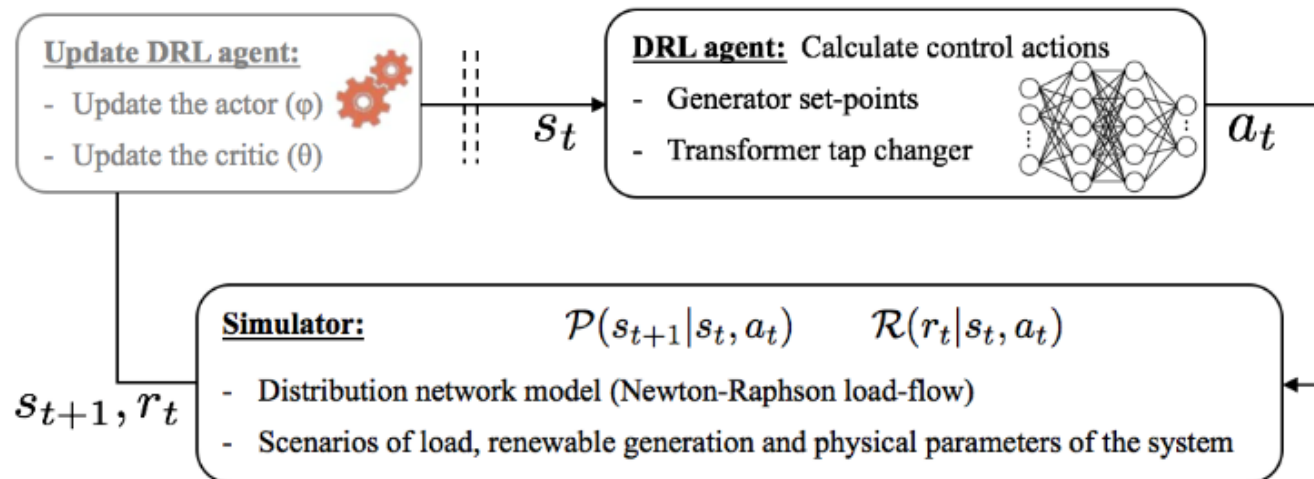
$$r_t = - \sum_{g \in \mathcal{G}} (C_Q |\Delta Q_{g,t}| + C_P |\Delta P_{g,t}|) - C_{TR} |\Delta Tap_t| + \begin{cases} +R_{pos}, \forall V_{n,t} \in [\underline{V}, \bar{V}] \\ -R_{neg}(\underline{V} - V_{n,t}), \forall V_{n,t} < \underline{V} \\ -R_{neg}(V_{n,t} - \bar{V}), \forall V_{n,t} > \bar{V} \end{cases}$$



**Tunning the coefficients of reward function**

## Deep Reinforcement Learning (DRL) for voltage control [7]

- To **boost the learning capabilities** of the RL agent, it is complemented by the **actor-critic architecture**.
- The goal of the actor is to **learn a deterministic policy** which selects the action  $a$  based on the state  $s$ .
- The quality of **the action is estimated by the critic**.
- Actor and critic functions are estimated using **deep neural networks**.



Training of the proposed DRL-based voltage control technique

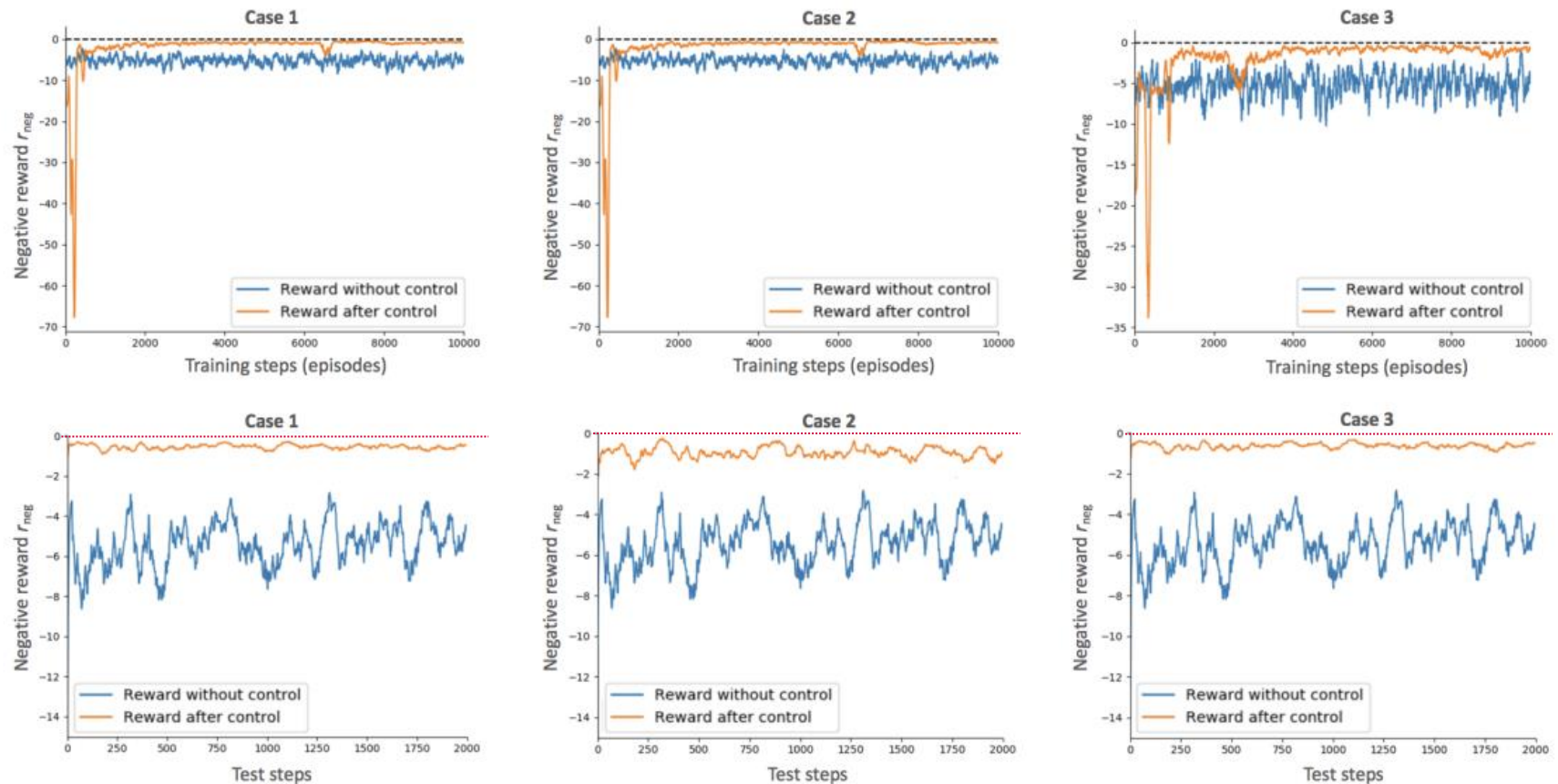
- The proposed DRL-based voltage control approach is tested on a **real MV distribution system in Benin [8]**.
- Vèdoko HV/MV substation alongside **5 representative MV feeders** connected to it has been modelled.
- It consists of **100 buses** and feeds an overall demand equal to 26.3 MW and 12.7 Mvar.
- 10 DG units (of 4 MW) are considered (two DGs per feeder).
- The DRL-based agent is **trained on 10000** different working states of **nodal load demands and DG powers**.
- The DRL-based agent is **tested on 2000 unseen new samples**.
- The **environment/simulator is changing** in each sample to consider the **distribution network model uncertainty impacts**.
- A **random error is added to take into account the uncertainty in DG power forecasts**.

## Studied test cases and obtained results

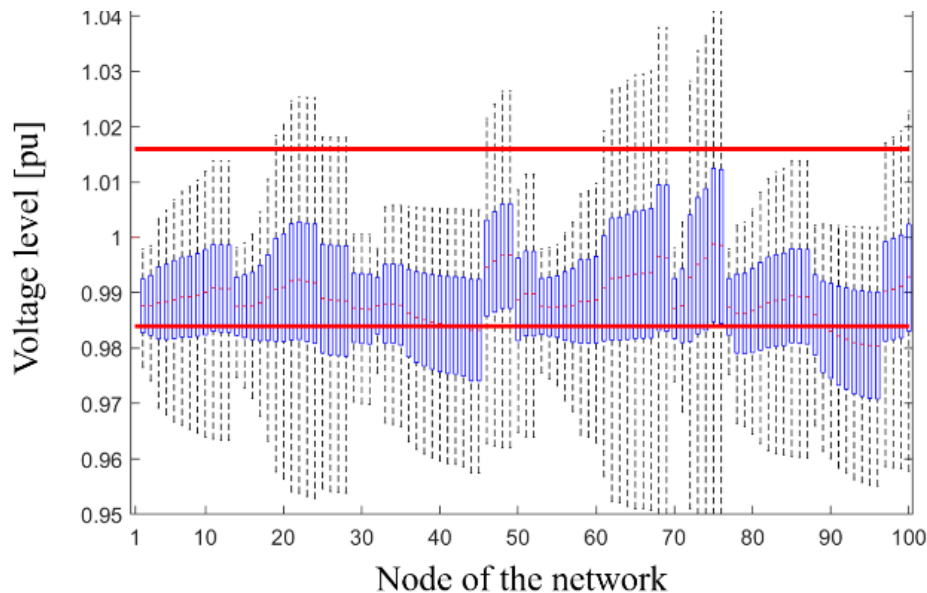
**Case 1:** Uncertainty sources are **disregarded** in both **training and test phases**;

**Case 2:** Uncertainty sources are **disregarded during the training**, but **considered in test phase**;

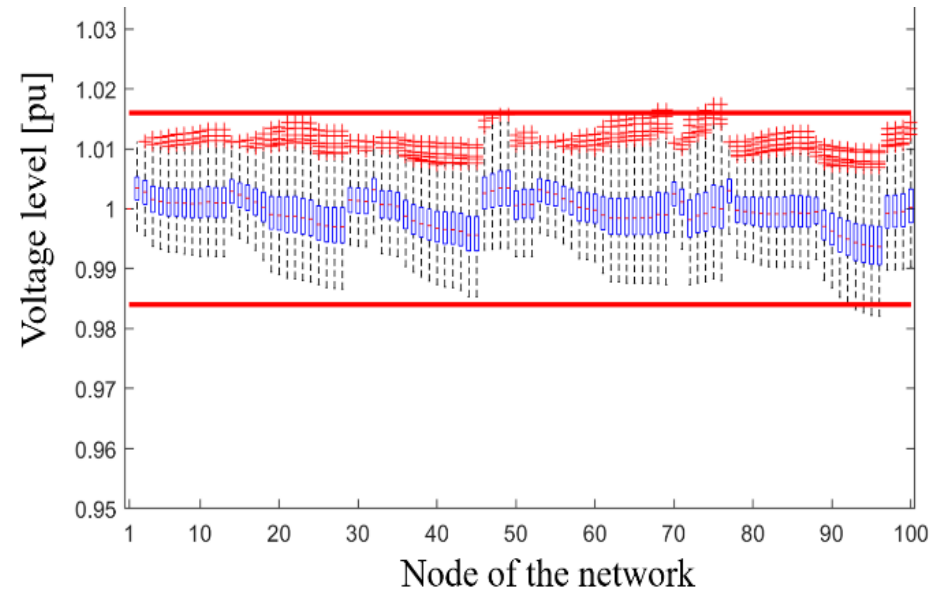
**Case 3:** Uncertainty sources are **considered in both training and test phases**.



Initial voltages



Corrected voltages



**Initial voltage violations are effectively removed  
while addressing the considered uncertainty sources**



- A **centralized** approach for voltage constraints management in distribution networks based on **deep reinforcement learning** is proposed.
- It considers the **uncertainties relating to the network parameters/models** as well as the **network operating points** while taking its corrective control decisions.
- The proposed method is tested on a **real MV distribution feeders** in Benin.
- ✓ Simulation results demonstrate that the proposed DRL-based method can **effectively manage the voltage constraints subject to different sources of uncertainty**.
- ✓ The DRL agent **trained in off-line mode** can **take control decisions in real time**.
- ✓ The **DRL-agent progressively learns the optimal control policy** through interactions with the environment in a **model-free fashion**: without relying on the analytical network models.

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- [2] Capitanescu, F.; Bilibin, I.; Ramos, E. R. “A comprehensive centralized approach for voltage constraints management in active distribution grid, IEEE Trans. Power Syst. 2013, 29, 933–942.
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- [4] Valverde, G.; Van Cutsem, T. “Model predictive control of voltages in active distribution networks”, IEEE Trans. Smart Grid 2013, 4, 2152–2161.
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- [6] Bakhshideh Zad, B.; Toubeau, J.-F.; Vallée, F. “Chance-constrained based voltage control framework to deal with model uncertainties in MV distribution systems”, *Energies* 2021, 14.
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**Thanks for your attention**

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