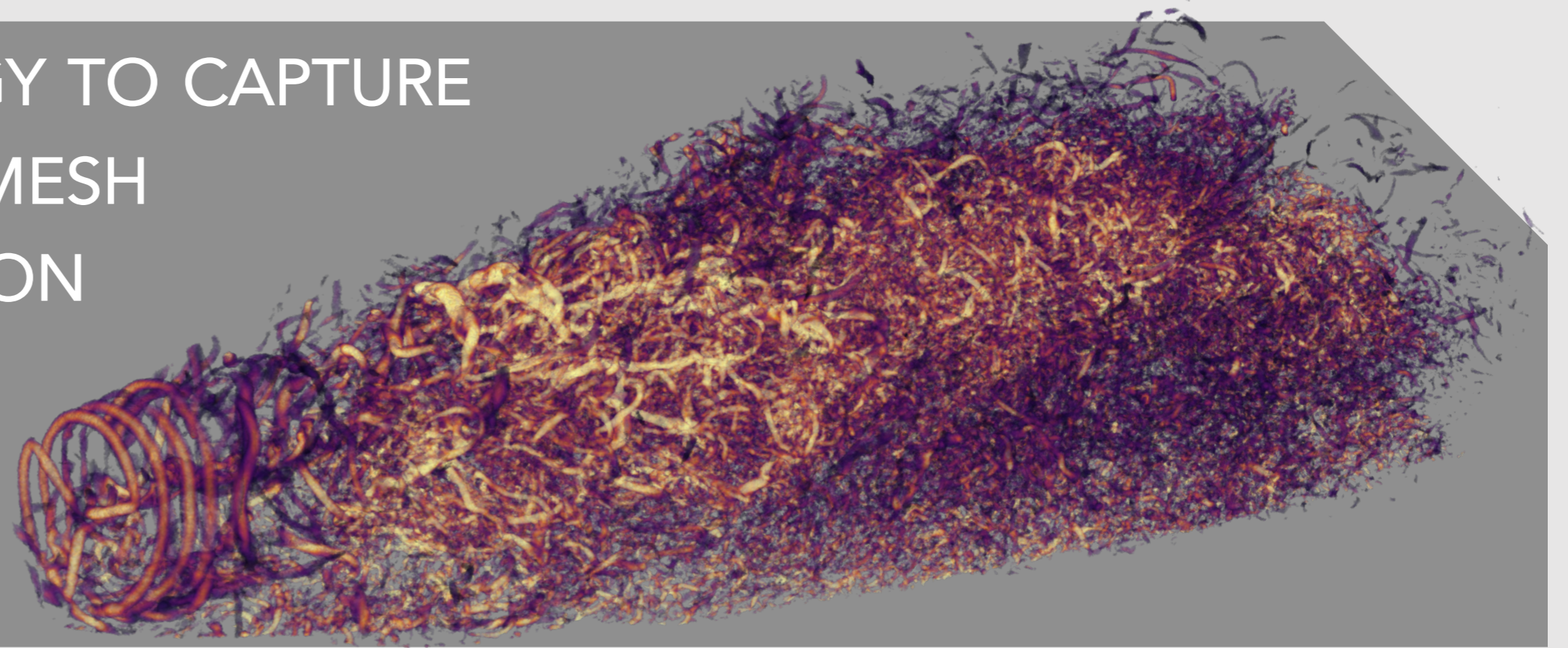


# A NEW WAKE DETECTION METHODOLOGY TO CAPTURE WIND TURBINE WAKES USING ADAPTIVE MESH REFINEMENT AND LARGE EDDY SIMULATION

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## 1 ► CONTEXT

In the context of wind farms, numerical prediction of turbulent vortical wakes released downstream of wind turbines constitutes a challenging problem.

- Need for **predictive tools** to model wind turbine wakes

### Problematics

Properly capturing complex, three-dimensional, unsteady wakes involves:

- A **Large Eddy Simulations** approach [1]
  - A adequate mesh [2]
  - A compromise between computational cost and wake accuracy
- **Adaptive Mesh Refinement** is applied in the wake region

### Objectives

Development of a new wake detection method  
Application of AMR strategy within the wake envelope

## 3 ► SETUP

### Flow solver

**YALES2** [3,4,5]

- Low Mach number Navier Stokes equations solver
- 4<sup>th</sup> order central finite volume method ; 4<sup>th</sup> order time integration
- Turbulence model: **SIGMA** [6]

### Wind turbine

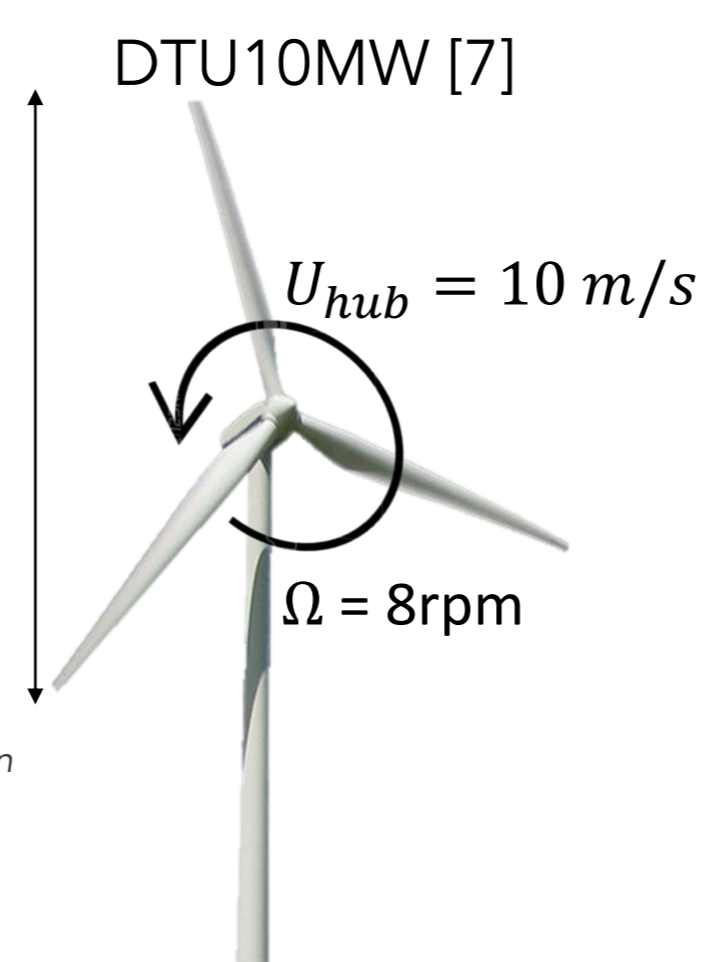
- DTU10MW,  $\lambda_{opt} = 7.5$
- ALM: 50 points per blade  $D = 178.3m$

### Turbulence

- Precursor Database Method [8,9]
- $u(z) = \frac{u_r}{k} \log\left(\frac{z+z_0}{z_0}\right)$   $z_0 = 0.02 m$

### Configuration

- 1 Wind turbine  $\left\{ \begin{array}{l} \text{Reference} \\ \text{AMR} \end{array} \right\}$  Comparison
- 2 Wind turbines  $\left\{ \begin{array}{l} \text{Reference} \\ \text{AMR} \end{array} \right\}$  Comparison
- Time-varying yaw misalignment:  $\gamma = 15 \sin\left(\frac{\pi}{60} + t\right)$



## 5 ► CONCLUSION & PERSPECTIVES

### Methodology:

- Allows to properly capture wind turbine wakes
- Define an accurate wake envelope
- Negligible cost

### AMR:

- Exhibits similar physical precision
- 30% to 50% computational **cost reduction**

Cost reduction for the same physical precision

### Perspectives:

- A more dynamic mesh refinement approach
- A non user-dependent target cell size [2]

## 2 ► METHODOLOGY

### Detection

Strategy: **progress variable**  $\phi$  transported on the Eulerian grid with a source term  $\dot{\omega}_\phi$  in the rotor region:

$$\frac{\partial \rho \phi}{\partial t} + \nabla \cdot (\rho \mathbf{u} \phi) = \nabla \cdot (\rho D_\phi \nabla \phi) + \dot{\omega}_\phi$$

Average wake position is given by overlaying the progress variable over fluid iterations

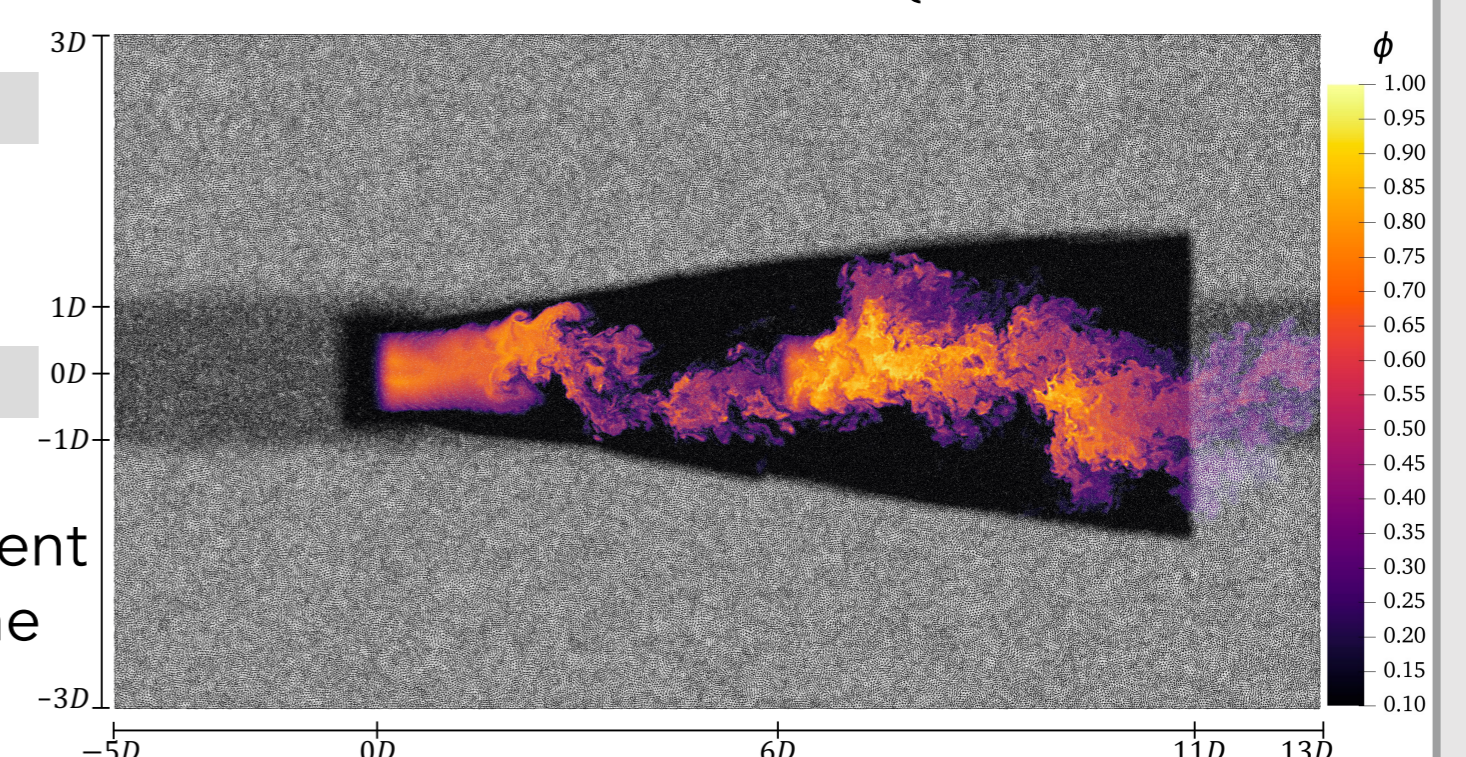
$$\hat{\phi}(\mathbf{x}, t + dt) = \max(\hat{\phi}(\mathbf{x}, t), \phi^*(\mathbf{x})) \text{ with } \phi^*(\mathbf{x}) = \begin{cases} 1, & \text{if } \phi(\mathbf{x}) > 0.1 \\ 0, & \text{if } \phi(\mathbf{x}) \leq 0.1 \end{cases}$$

### Mesh size

User-dependent target value [2]

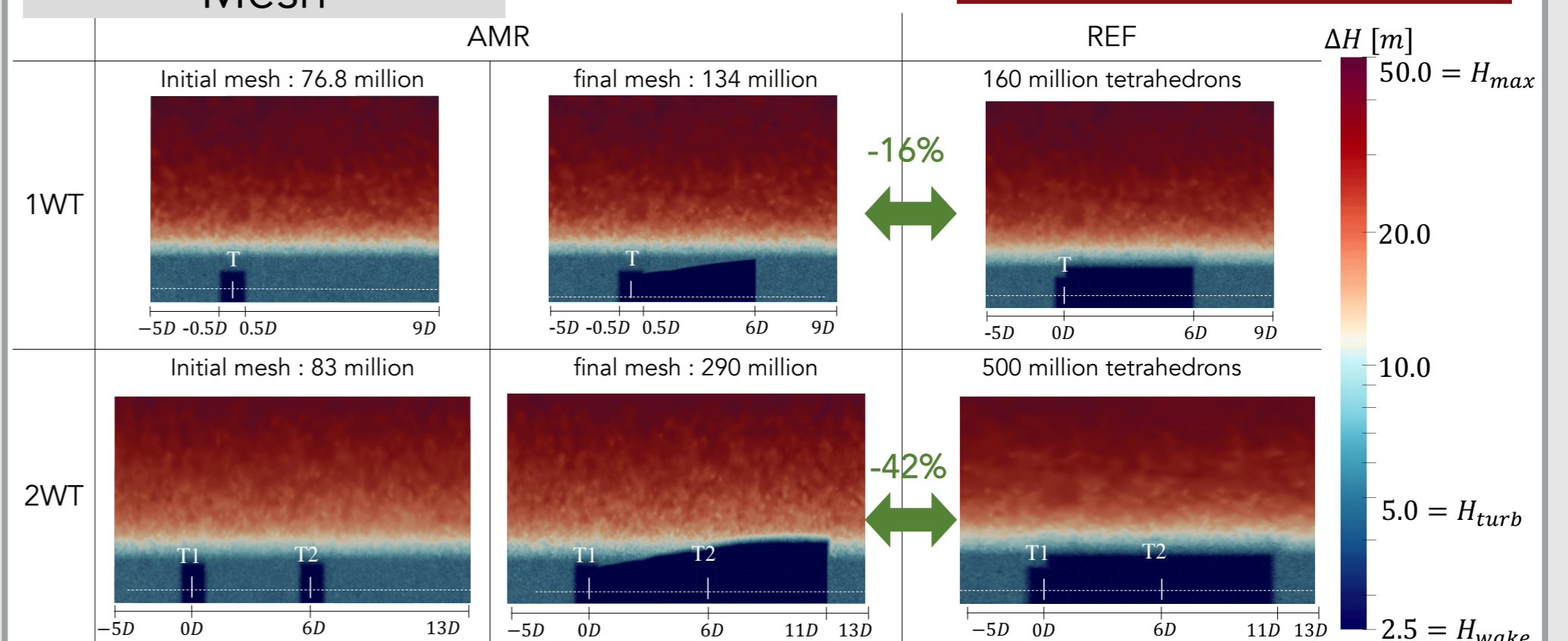
### Frequency

Occuring iteratively.  
Triggered when current mesh too far from the objective mesh.

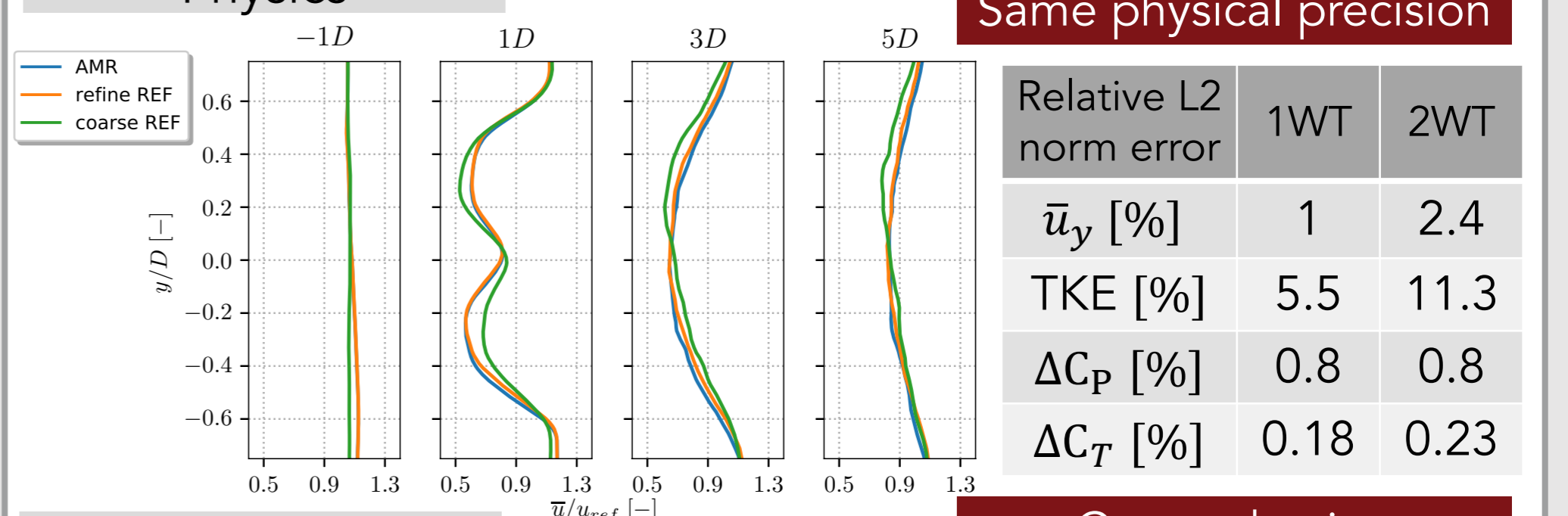


## 4 ► RESULTS

### Mesh



### Physics



### Cost

setup	cases	#elem [x10 <sup>6</sup> ]	physical time [s]	adapt time [%]	khCPU
1WT	REF	160	1440	/	24.2
	AMR	77-135	1440	3.5	16.3
2WT	REF	500	2880	/	174
	AMR	83-290	2880	2.1	83

## 6 ► REFERENCES & AKNOWLEDGMENTS

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