Q-balls and charged *Q*-balls in a two-scalar field theory with generalized Henon-Heiles potential

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(Received 28 February 2024; accepted 8 April 2024; published 30 April 2024)

We construct Q-ball solutions from a model consisting of one massive scalar field ξ and one massive complex scalar field ϕ interacting via the cubic couplings $g_1\xi\phi^*\phi + g_2\xi^3$, typical of Henon-Heiles-like potentials. Although being formally simple, these couplings allow for Q-balls. In one spatial dimension, analytical solutions exist, either with vanishing or nonvanishing ϕ . In three spatial dimensions, we numerically build Q-ball solutions and investigate their behaviors when changing the relatives values of g_1 and g_2 . For $g_1 < g_2$, two Q-balls with the same frequency exist, while $\omega = 0$ can be reached when $g_1 > g_2$. We then extend the former solutions by gauging the U(1) symmetry of ϕ and show that charged Q-balls exist.

DOI: 10.1103/PhysRevD.109.076029

I. INTRODUCTION

Scalar fields appear in numerous sectors of physics as solid state physics, elementary particles, supersymmetry, gravity and cosmology. On the theoretical side, numerous classical solutions have been obtained in field theories involving scalar fields. Among them are solitonlike solutions, and perhaps the most popular ones are Q-balls, which are nontopological solitons appearing in classical field theories presenting a global symmetry [1,2]. A simple example involves just one complex scalar field, ϕ , with a potential invariant under the U(1) phase group and obeying some conditions derived in [1]. In this pioneering work it is demonstrated that the existence of Q-balls needs highdegree interacting terms, e.g., at least $(\phi^*\phi)^2$, which are not compatible with renormalization. The standard Q-ball in three spatial dimensions is spherically symmetric and is characterized by the ansatz $\phi(r) = \exp(i\omega t)f(r)$ with a constant harmonic frequency ω and a real, radial, function f(r) which can present zero or a finite number of nodes. The fundamental solution has no node and decreases monotonically from a finite value at the center, say f(0), to zero at spatial infinity. Node solutions are interpreted as excitations of the fundamental solution. Enlarging the ansatz to an axial symmetry allows for other types of Q-balls, namely spinning solutions [3]. The nonlinear character of the field equations requires to solve them by approximation or numerical techniques, even when the interaction is represented by a polynomial in the squared modulus $\phi^*\phi$.

The minimal theory involving a single self-interacting complex scalar field can be enlarged in several directions, namely by considering two or more extra complex fields (see e.g., [4]) or by supplementing electromagnetism. "Gauged versions" of the Klein-Gordon theory have been proposed for a long time [5,6], leading naturally to charged Q-balls as solutions. In the recent years several models containing scalar fields with U(1)-gauge symmetry were proposed, see namely [7–10]. Different types of classical solutions were constructed and possible applications of them in astrophysics/cosmology emphasized. A recent review of the topic and of its applications can be found in [11] where a complete list of references can by found.

One of the simplest way along the latter direction consists in supplementing the minimal theory by one real massive scalar field ξ . For example, the Friedberg-Lee-Sirlin model [12] provides an interesting case of a renormalizable two-component scalar field theory with natural interaction terms of degree four in the two fields; $\mathcal{L} = \partial_{\mu} \phi^* \partial^{\mu} \phi + \frac{1}{2} \partial_{\mu} \xi \partial^{\mu} \xi - d^2 \xi^2 \phi^* \phi + \frac{g^2}{8} (\xi^2 - \xi^2_{vac})^2$ with

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d and *g* coupling constants. In this model, the complex scalar becomes massive due to the coupling with the real scalar field, since the latter has a finite vacuum expectation value ξ_{vac} generated via a symmetry-breaking potential. In this case both the harmonic time dependence of the complex scalar and its coupling with the real field allow for *Q*-balls to exist. Extensions gauging the U(1) symmetry of this model have been emphasized, see e.g., [13] and references therein.

In this paper, we will focus on a model involving a real and complex scalar field proposed in [11,14],

$$S = \int d^{D+1}x \bigg[\partial_{\mu} \phi^{*} \partial^{\mu} \phi - m^{2} \phi^{*} \phi + \frac{1}{2} \partial_{\mu} \xi \partial^{\mu} \xi - \frac{1}{2} M^{2} \xi^{2} + g_{1} \xi \phi^{*} \phi + g_{2} \xi^{3} \bigg], \qquad (1.1)$$

with Minkowski metric $\eta = (+ - --)$ and where g_1 and g_2 are positive real coupling constants. In contrast to [12], the masses of the two fields are set by hand and the polynomial interaction is cubic in the two scalar fields. This interaction term is inspired by the celebrated Heinon-Heiles potential in classical mechanics [15].

In [14], the model (1.1) was studied in one spatial dimension and an explicit solution was obtained for $g_2 = g_1$. In this work the cases D = 1 and D = 3 will be studied in Secs. III and IV respectively, without restriction on g_2 and g_1 , after having defined our ansatz in Sec. II. Finally, the U(1) symmetry of the model will be gauged, and charged *Q*-balls will be built in Sec. V.

II. Q-BALL ANSATZ

We are interested in classical solutions associated with the model (1.1). Noting r(z) the *D*-dimensional radial variable in D > 1 (D = 1), we make a nonrotating *Q*-ball ansatz for ϕ and also ask for a radial form for ξ ,

$$\phi = e^{i\omega t} \frac{F(r)}{\sqrt{2}}, \qquad \xi = G(r), \qquad (2.1)$$

with F and G being real functions. The corresponding equations of motion take the form,

$$F'' + \frac{D-1}{r}F' = \Omega^2 F - g_1 F G,$$
 (2.2a)

$$G'' + \frac{D-1}{r}G' = M^2G - \frac{g_1}{2}F^2 - 3g_2G^2, \qquad (2.2b)$$

with

$$\Omega^2 = m^2 - \omega^2. \tag{2.2c}$$

For the regular solutions of *Q*-ball-type that we are interested in, the nonlinear system above has to be solved

with the boundary conditions,

$$F'(0) = 0,$$
 $G'(0) = 0,$ $G(0) = C,$
 $F(\infty) = 0,$ $G(\infty) = 0,$ (2.3)

while the frequency ω has to be fine-tuned as function of the central value *C*. It is convenient to use *C* as a control parameter. The case D = 1 deserves a separate study since analytical solutions exist, see next section. Although the case D = 3 is physically motivated, the field equations do not admit (up to our knowledge) analytical solutions, but the equations can be treated by numerical methods. We integrate the equations numerically by using the solver COLSYS [16]. The axis of radial coordinate was discretized by about 400 points and the solutions were obtained with an error less than 10^{-8} .

The *Q*-ball solutions can be characterized by several physical quantities, namely their energy \tilde{E} and conserved Noether charge \tilde{Q}_N . They are given respectively by the integrals,

$$\tilde{E} = \int_{\mathbb{R}^D} d^D x T_0^0, \qquad \tilde{Q}_N = \int_{\mathbb{R}^D} d^D x J^0, \qquad (2.4)$$

where the definition of T_0^0 is standard and where $J^0 = i(\phi \frac{\partial}{\partial t} \phi^* - \phi^* \frac{\partial}{\partial t} \phi)$. With the ansatz above, $\tilde{E} \equiv V_{D-1}E$ and $\tilde{Q}_N \equiv V_{D-1}Q$, where V_{D-1} is the volume of the (D-1)-sphere $(V_0 = 1, V_2 = 4\pi)$ and where E and Q are evaluated by simple integrals,

$$E = \int_0^\infty dr \, r^{D-1} \left(\frac{1}{2} (F'^2 + (m^2 + \omega^2) F^2 + G'^2 + M^2 G^2) - \frac{g_1}{2} F^2 G - g_2 G^3 \right),$$
(2.5)

$$Q = \omega \int_0^\infty dr \, r^{D-1} F^2. \tag{2.6}$$

III. *D* = 1: HENON-HEILES EFFECTIVE HAMILTONIAN

A. Effective potential

For D = 1, the equations of motion are equivalent to the equations of motion of the Henon-Heiles-type Hamiltonian,

$$H = \frac{1}{2}(P_F^2 + P_G^2 - \Omega^2 F^2 - M^2 G^2) + \frac{g_1}{2}F^2 G + g_2 G^3,$$
(3.1)

with $P_F = F'$ and $P_G = G'$, the derivative being taken with respect to the spatial coordinate *z*, here seen a the temporal parameter of the effective Hamiltonian.

The solutions of the equations of motion are therefore related to the movement of an effective particle in the potential,

$$V(F,G) = -\frac{\Omega^2}{2}F^2 - \frac{M^2}{2}G^2 + \frac{g_1}{2}F^2G + g_2G^3, \quad (3.2)$$

that is

$$F'' = -\partial_F V, \qquad G'' = -\partial_G V. \tag{3.3}$$

We note that V(-F, G) = V(F, G) and that $\partial_G V(F, G < 0) > 0$; no bounded trajectory is expected if G becomes negative, however F may change sign. V has a local maximum in (F, G) = (0, 0) for all values of the parameters, and V(0, 0) = 0. If $\frac{g_1}{g_2} \le 3\frac{\Omega^2}{M^2}$, V has a saddle point in $(0, \frac{M^2}{3g_2})$ and no other extremal point. The most favorable situation for the existence of nontrivial solutions is

$$\frac{g_1}{g_2} > 3\frac{\Omega^2}{M^2},$$
 (3.4)

where V has a minimum in $(0, \frac{M^2}{3g_2})$, the minimal value being $-\frac{M^6}{54g_2^2}$, and where V has also a saddle point in $(\frac{\Omega^2}{g_1}, \sqrt{2\frac{\Omega}{g_1}}\sqrt{M^2-3\frac{g_2}{g_1}\Omega^2})$.

We remark that the original Henon-Heiles Hamiltonian [15] would be obtained by setting $M^2 = \Omega^2 = -1$, $g_1 = 2$ and $g_2 = -1/3$. This case will not be investigated here since solitonlike solutions are rather found for positive M^2 and Ω^2 , but it has motivated a tremendous number of studies, to which we refer the reader. Many references and original results regarding the existence and types of trajectories in the original Henon-Heiles model can be found in [17,18].

B. Explicit solutions

The profiles of F(z) and G(z) we look for reach their global maxima in F(0) and G(0) respectively. Moreover, they tend to zero as $z \to \pm \infty$: $F(\pm \infty) = G(\pm \infty) = 0$ and $(P_F, P_G) = (0, 0)$ as (F, G) = (0, 0) so the motion of the effective particle has zero total energy. The V = 0 curve has the equation,

$$F^2 = G^2 \frac{M^2 - 2g_2 G}{g_1 G - \Omega^2},$$
(3.5)

which, imposing $F^2 \ge 0$, is defined for

$$G = \left\{ 0, \frac{\Omega^2}{g_1} < G < \frac{M^2}{2g_2} \right\}.$$
 (3.6)

As sketched in Fig. 1, the soliton starts from (0, 0) at $z \to -\infty$, then (F, G) reach the V = 0 curve at z = 0, that



FIG. 1. Effective potential (3.2) and typical allowed solutions (solid lines). The sketched solutions actually correspond to (3.7) (red), (3.8) (purple) and (3.10) (green). The displayed shape for V has been obtained for M = 2.11166, m = 1, $g_1 = 2$, $g_2 = 1$, $\Omega = 0.8$, i.e., a configuration for which the three solutions may exist. The plot was made using GeoGebra software.

is F(0) and G(0) linked by (3.5), and finally turn back to (0,0) at $z \to +\infty$. If G(0) reaches the maximal value $\frac{M^2}{2g_2}$, then the only allowed solution is F = 0. If G(0) approaches the minimal value $\frac{\Omega^2}{q_1}$, then F(0) becomes larger and larger.

Analytical solutions can be pointed out. First, a solution in which F is trivial exists for any nonzero value of the parameters,

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$$F(z) = 0, \tag{3.7a}$$

$$G(z) = \frac{M^2}{2g_2} \frac{1}{\cosh^2\left(\frac{M}{2}z\right)}.$$
 (3.7b)

This solution is denoted HH_2 in [19]. This is the only known soliton solution with arbitrary ratio $\frac{g_1}{g_2}$ and arbitrary M and ω . Other solutions with arbitrary ratio $\frac{g_1}{g_2}$, denoted HH_1 in [19], have a fixed value for M and ω . Hence, they are not relevant candidates to generate Q-ball solutions in D = 3.

Regarding solutions with nonvanishing *F* and *G*, Hamiltonian (3.1) is known to be separable in three specific cases; $6g_2 = g_1$ and $\Omega^2 = M^2$ (Sawada-Kotera), $g_2 = \frac{8}{3}g_1$ and $M^2 = 16\Omega^2$ (Kaup-Kupershmidt), $g_2 = g_1$ and Ω^2 , M^2 arbitrary (KdV5) [20]. The corresponding Hamilton-Jacobi equations may be solved in terms of hyperelliptic integrals [20,21].

An other path to build solutions was followed in [19], in which it is shown that solitary-wave-type solutions of Riccati equations may be used to build solitonlike solutions of Eqs. (2.2a) and (2.2b). Explicit soliton solutions of Sawada-Kotera and Kaup-Kuperschmidt cases introduced

in [20] can be found in Table 1 of Ref. [19] under the name SK_m —in the notations of the latter reference, they are obtained for $\epsilon = 1$ and $\epsilon = \frac{1}{16}$, respectively. When $g_2 = g_1$, the solution denoted KdV5₁ in [19] (KdV5 in [20]) and also given in [14] may be quoted,

$$F(z) = \frac{2\Omega}{g_1} \frac{\sqrt{M^2 - 4\Omega^2}}{\cosh(\Omega z)},$$
 (3.8a)

$$G(z) = \frac{2\Omega^2}{g_1} \frac{1}{\cosh^2(\Omega z)}.$$
 (3.8b)

Solution (3.8) is well-defined for

$$\omega^2 \ge m^2 - \frac{M^2}{4},\tag{3.9}$$

and it reduces to (3.7) when the lower bound is reached. Note that parameters such that $M \ge 4m$ may in principle allow for $\omega = 0$ solutions.

The shapes of all analytical solutions of soliton type are listed in Table 1 of [19]. They correspond to specific values of the ratio $\frac{\Omega^2}{M^2}$ in terms of g_1 and g_2 . For example, we find that the solution called HH_1 in [19] solves our equations of motion for the following explicit values of the parameters:

$$F(z) = \frac{6\Omega}{g_1} \sqrt{2\left(3\frac{g_2}{g_1} - 1\right)} \frac{\sinh(\Omega z)}{\cosh^2(\Omega z)},$$
 (3.10a)

$$G(z) = \frac{6\Omega^2}{g_1} \frac{1}{\cosh^2(\Omega z)},$$
(3.10b)

with $M^2 = 2\Omega^2 \left(9\frac{g_2}{g_1} - 1\right)$, and $\frac{g_2}{g_1} > \frac{1}{3}$. (3.10c)

This last solution has $P_F(0) \neq 0$, and hence do not reach the V = 0 curve before turning back to the origin; $G \in [0, \frac{6\Omega^2}{g_1}]$. Solutions similar to (3.10) will not be investigated further here since our aim is to build *Q*-balls at D = 3: To reach this goal we have to consider ω as unspecified, and *a priori* independent of the coupling constants. The only solutions allowing for arbitrary *M* and ω are (3.7) and (3.8).

Other solutions may also be constructed numerically, but this task will be performed at D = 3; the D = 1 case being seen as a test case to analytically understand the existence and types of solutions.

IV. D = 3: Q-BALLS

The four physical parameters m, M, g_1 , and g_2 can be redefined by appropriate rescaling of the radial coordinate and of the two scalar fields. We will use this freedom to set m = 1 and $g_2 = 1$ in the rest of this work so that M, g_1 become the relevant parameters for the study of the solutions. The numerical analysis of the equations reveals that the spectrum of Q-balls depends significantly on M and g_1 .

A. A special solution

First, let us notice that the system (2.2) possesses a unique solution with F(r) = 0 and $G(r) \neq 0$ with no node. Because this solution play an important role in the classification of the solutions we find convenient to note it $G_0(r, M)$. It exists irrespectively of g_1 but depends on M.

Inspection of Eq. (2.2b) shows that the scaling relation $G_0(r, M) = M^2 G(Mr, 1)$ holds for any spatial dimension. Accordingly the function $G_0(r, M)$ smoothly approaches the null function in the limit $M \rightarrow 0$. We could not find a closed form for $G_0(r, M)$ but the following behaviors hold respectively close to the origin and in the asymptotic region:

$$G_0(r, M) = c_0 + \frac{c_0(M^2 - 3c_0)}{6}x^2 + \frac{c_0(M^2 - 3c_0)(M^2 - 6c_0)}{120}x^4 + o(x^6), \quad (4.1)$$

$$G_0(r,M)_{r\to\infty} \sim \frac{\mathrm{e}^{-Mr}}{r},\tag{4.2}$$

where c_0 is an arbitrary parameter. The soliton solution of interest has $G_0(0,1) \approx 1.3972$ so that $G_0(0,2) = 4G_0(0,1) \approx 5.5889$. In terms of the effective potential (3.2), it means that this solution has to be launched as initial condition from the level,

$$V(F(0) = 0, G_0(0, M)) = -\frac{M^2}{2}G_0(0, M)^2 + g_2G_0(0, M)^3$$

\$\approx 1.75148M^6, (4.3)

to reach the level zero $V_{\text{eff}} = 0$ in the limit $r \to 0$.

We remark that the solution (3.7) at the center is equal to 0.5 (resp. 2) for M = 1 (resp. M = 2); the larger values of $G_0(0)$ for D = 3 are due to the damping term $\frac{2}{r}G'$ in D = 3. The energy at r = 0 has indeed to be larger than 0 for the effective particle to reach G = 0 at infinity.

We notice that profiles such as (3.10), with nonzero F'(0) or G'(0), are not allowed in D = 3; a power expansion around the origin shows that only the boundary conditions (2.3) may lead to regular solutions at origin.

B. The case $g_1 = g_2$

For definiteness, let us first discuss the solutions in the case $g_1 = g_2$, owing that the explicit solution (3.8) exists for D = 1 and will be compared to the numerically obtained following solutions.



FIG. 2. Left: The central values F(0), G(0), the mass and the Noether charge as function of ω for D = 3, M = 1, $g_1 = 1$. Right: The same data for M = 2. For completeness we mention that the data used to generate this figure may be found at [22].

It is found that *Q*-ball solutions exist for a finite interval of the frequency ω , that is for $\omega \in [\omega_m, 1.0]$ where ω_m depends on the values *M*, g_1 . Several parameters characterizing the solutions available for the cases M = 1, $g_1 = 1$ and M = 2, $g_1 = 1$ are presented in Fig. 2. The following features are observed:

- (i) In the limit ω → 1.0, the two scalar functions F(r), G(r) uniformly tend to the zero function. However, these functions extend more in space and the convergence is slow in such a way that the mass and Noether charge diverge in this limit. This limit is Ω → 0 and the vanishing of F and G is coherent with (3.7);
- (ii) In the limit $\omega \to \omega_m$, the function F(r) tends uniformly to the null function. In this case the convergence is quick enough so that the Noether charge also approaches zero. By contrast the function $G(r) \to G_0(r)$ with $G(0) \to 5.5889$ (see above) and the mass remains finite in this limit;
- (iii) An increase of the parameter M leads to a decrease of ω_m , so to a larger interval of possible frequencies. This behavior is in qualitative agreement with (3.9).

Typical profiles of the functions F(r) and G(r) and of the effective energy density ϵ , defined as the integrand of (2.5), are presented in Fig. 3 for the case $g_1 = 1$, M = 2. The dashed and solid lines respectively correspond to $\omega = 0.9407$ and $\omega = 0.999$.

An algebraic reason for the occurrence of the minimal frequency ω_m is, so far, missing, in contrast to standard Q-balls where it is related to an argument of positivity of the effective potential. From our numerical results it can be guessed that the triplet of parameters F(0), G(0), and ω has to be fine-tuned in such a way that the corresponding level of the effective energy (4.3) is approached.

C. The case $g_1 > g_2$

The numerical analysis reveals that the pattern of solutions observed in the case $g_1 = g_2$ changes significantly when the two coupling constants are different. For this reason we find it convenient to analyze separately the cases $g_1 > g_2$ and $g_1 < g_2$. The results in this section are reported for the case M = 2. We checked that small changes of M do not affect the pattern, although the case $M \ll m$ will not be considered here.

When M = 2, and actually when M > m, the pattern looks similar to the case $g_1 = g_2$. Parametrizing again the solutions by the frequency ω , it turns out that solutions exist for $\omega \in [\omega_m, 1]$ where the minimal value ω_m decreases when g_1 increases; this is illustrated by Fig. 4 where the central values F(0), G(0) are reported versus ω for several



FIG. 3. Profiles of the functions F, G and the effective energy density ϵ for D = 3, M = 2, and $g_1 = 1$ for $\omega = 0.9407$ (dashed lines) and for $\omega = 0.999$ (solid lines).



FIG. 4. Left: The central values F(0) as function of ω for D = 3, M = 2 and several values of g_1 . Right: The corresponding values of G(0).



FIG. 5. Left: The central values F(0), G(0) and the soliton mass as function of ω for D = 3, M = 2, $g_1 = 2.0$.

values of g_1 . Interestingly, when g_1 is large enough, solutions exist for the full interval of frequencies $\omega \in [0, 1]$. In particular, the solutions corresponding to $\omega = 0$ are regular and real. Moreover, it is found that real solutions exist for $g_1 \ge g_c$ with $g_c \approx 1.68$. For $g_1 < g_c$ the branch of solutions terminates in a configuration F(r) = 0, $G(r) = G_0(r)$ for $\omega \to \omega_m$, in particular $G(0) \to 5.5889$. Some physical parameters characterizing the case $g_1 = 2$ are presented in Fig. 5.

D. The case $g_1 < g_2$

Using again M = 2 and the frequency ω as parameter, it is found for $g_1 < 1$ that families of *Q*-balls exist for $\omega \in [\omega_m, 1.0]$. However, a new kind of phenomenon appears which is illustrated by Fig. 6. It turns out that the pattern of solutions presents two branches in ω that meet into the same solution for $\omega \to \omega_m$. In other words, two solutions with different values of F(0), G(0), and M correspond to the same frequency.

Details of the solutions corresponding to $g_1 = 0.5$ are presented in Fig. 7. Let us finally point out that the minimal frequency ω_m increases while decreasing g_1 . *Q*-balls do likely not exist for $g_1 < 0.35$.

V. CHARGED Q-BALLS

Among the possible extensions of our model is the promotion of the global U(1) symmetry to a gauge invariance. Here we apply the procedure to the model (1.1). As usual, the gauging is achieved by replacing the partial derivative $\partial_{\mu}\phi$ in (1.1) by a covariant derivative $D_{\mu}\phi = (\partial_{\mu} - ieA_{\mu})\phi$. The electromagnetic potential is noted A_{μ} and *e* represents the coupling constant. A Maxwell-Faraday Lagrangian is also added.

Completing the ansatz (2.1) by a spherically symmetric electric potential $A_0 = V(r)$, $A_{i\neq 0} = 0$, the field equations now read

$$F'' + \frac{D-1}{r}F' = (m^2 - W^2)F - g_1FG,$$
 (5.1a)

$$G'' + \frac{D-1}{r}G' = M^2G - \frac{g_1}{2}F^2 - 3g_2G^2, \qquad (5.1b)$$

$$W'' + \frac{D-1}{r}W' = \frac{e^2}{2}WF^2,$$
(5.1c)

with
$$W(r) \equiv \omega - eV(r),$$
 (5.1d)

to be solved with the boundary conditions (2.3) supplemented by W'(0) = 0. The quantity

$$\beta \equiv \omega - eV(\infty) \tag{5.2}$$



FIG. 6. Left: The central values F(0) as function of ω for D = 3, M = 2, and several values of g_1 . Right: The corresponding values of G(0).

plays the role of ω in the last section. The electric field V(r) is characterized by the chemical potential $\Phi \equiv V(r \rightarrow \infty) - V(0)$ and by the electric charge Q_E such that $V(r \rightarrow \infty) \sim V(\infty) - \frac{Q_E}{r}$. The electric charge is directly related to the Noether charge: $Q_E = e\tilde{Q}_N$ by Eq. (5.1c).

In our numerical study, we assume D = 3 and normalize r and ϕ such that m = 1, $g_2 = 1$ as previously. Along their uncharged counterparts, charged Q-balls exist in our model for $\beta \in [\beta_m, 1]$. A priori, β_m depends on g_1 , M, e. We constructed several families of charged Q-balls and found, surprisingly, that the minimal frequency β_m was not dependent on the electric coupling constant e. In [2] it was pointed out already that, when the electric coupling e increases, the solitons have tendency to disappear for large



FIG. 7. Left: The central values F(0), G(0) and the mass as function of ω for D = 3, M = 2, $g_1 = 0.5$ (the Noether charge is roughly equal to the mass all along). a and b label the two different branches of solutions.

enough coupling of the scalar field ϕ to the electric field. This has been recently demonstrated analytically by using thin-wall approximation in [23]. However, these last two studies couple a single field to a U(1) field. Static charged *Q*-balls were first investigated in the Friedberg-Lee-Sirlin model in [24] and the augmentation of β_m with *e* was numerically found in [25]. To our knowledge, the existence of static charged *Q*-balls in a Henon-Heilesinspired potential has never been show before, and understanding the independence of β_m on *e* would deserve further studies.

At the approach $\beta \rightarrow \beta_m$, the pattern of solutions is similar to the uncharged case; the electric potential tends to a constant so that Φ and Q_E tend to zero. The influence of the charge is more pronounced in the region $\beta \sim 1$. In this limit, the electric parameters Φ , Q_E increase while the scalar fields F(r), G(r) do not approach the null function and remain finite. This can be understood by the fact that, to compensate the electric repulsion, a minimal amount of (attractive) scalar field is necessary. Both phenomenon are illustrated by Fig. 8 for M = 2, e = 0.1 and for two values of the coupling constant g_1 .

The evolution of the solutions when increasing the parameter *e* comes out as a natural question which we investigated for a few values of g_1 . When *e* increases, the central values of the scalar fields F(0), G(0) increases and have tendency to depend weakly on β . For instance we found that they approach respectively the values $F(0)_{\beta=\beta_m}$ and $G(0)_{\beta=\beta_m}$ already for $e \sim 1$. This feature is illustrated by Fig. 9 in the case $g_1 = 2$. The same phenomenon holds for $g_1 = 1$; in this case $F(0)_{\beta=\beta_m} \sim 0$ and $G(0)_{\beta=\beta_m} \approx 5.585$. We limited our numerical work to $e \leq 1$ but believe that these features hold for other values of g_1 and may persist for larger values of *e*.



FIG. 8. Left: Some parameters of charged Q-balls as functions of β for $g_1 = 1$, M = 2, and e = 0.1. Right: Same for $g_1 = 2$.



FIG. 9. Left: Central value F(0) as functions of β for $g_1 = 2$, M = 2 and several values of e. Right: Same for the value G(0).

VI. SUMMARY

We have shown that the model presented in [14], made of one massive scalar field ξ and one massive complex scalar field ϕ interacting via the cubic couplings $g_1\xi\phi^*\phi + g_2\xi^3$, shows *Q*-balls as classical solutions. In one spatial dimension, the model's effective dynamics is that of a particle in a generalized Henon-Heiles potential. We have proposed three analytical solutions of solitary-wave type. We have also shown the existence of a rich pattern of *Q*-balls with spherical symmetry in three spatial dimensions, which is somewhat surprising regarding the simplicity of the couplings. The *Q*-ball with vanishing ϕ has a particular status since most of the solutions we find reduce to this *Q*-ball when ω approaches its lower bound. When $g_1 < 0.35g_2$, no *Q*-ball exists. When $g_1 \ge 1.68g_2$ however, *Q*-balls exist up to $\omega = 0$ with nonzero values for both ϕ and ξ . Finally, we showed that solutions continue to exist when a coupling to an electric field is supplemented and we have discussed how their domain of existence evolves in response to the electric coupling constant. We leave the exploration of solutions with rotation or nodes, or of boson-star type, for future works.

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